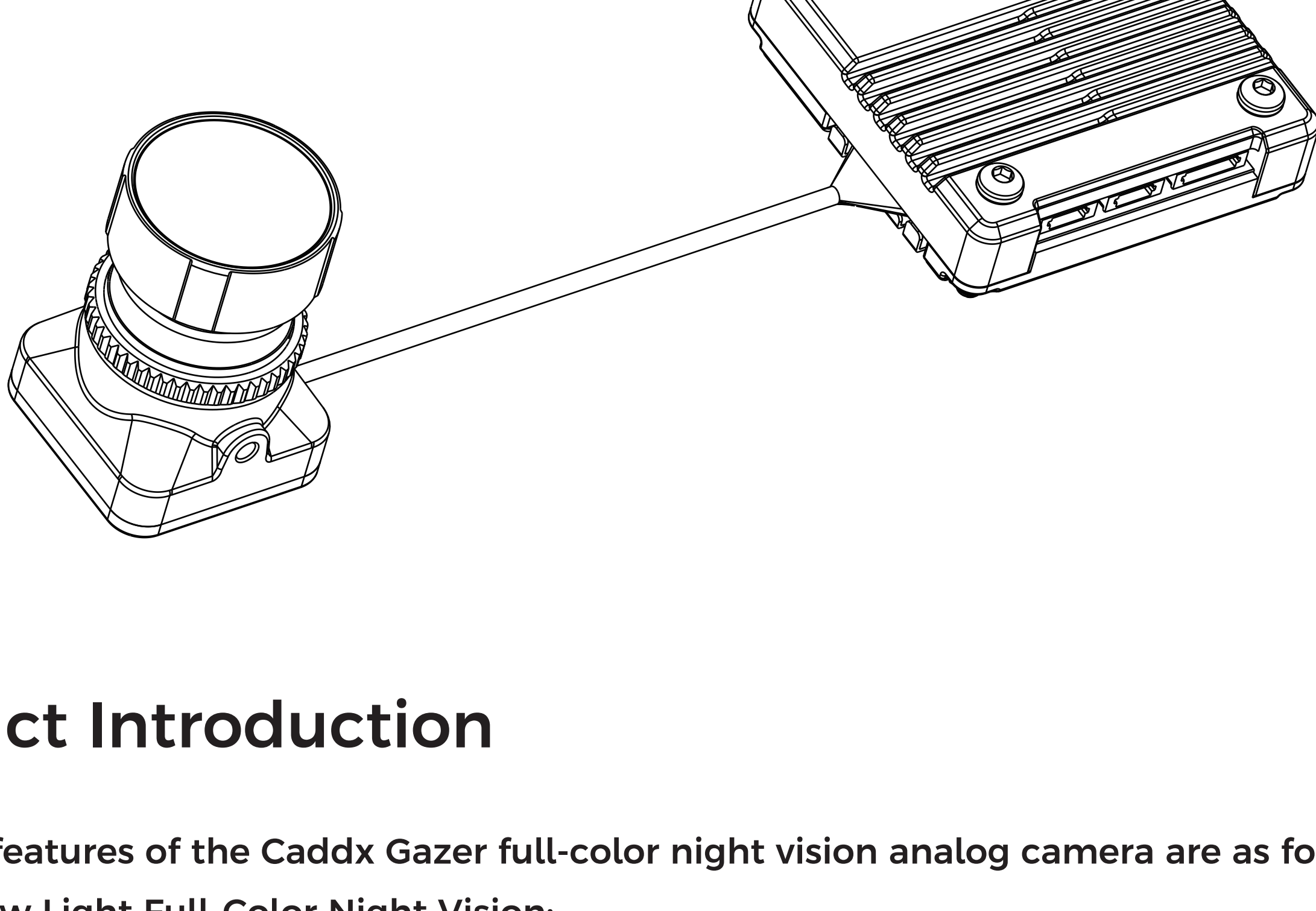


Caddx Gazer

Quick Start Guide

V1.0



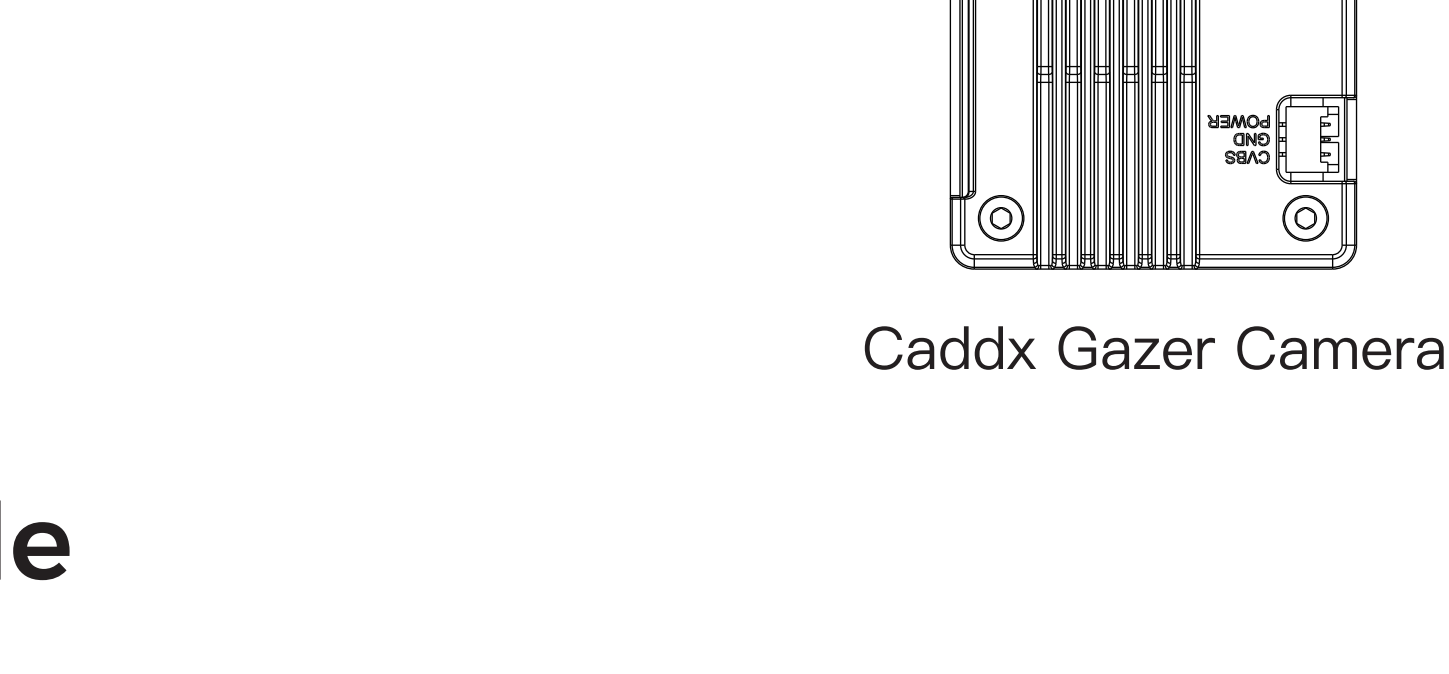
Product Introduction

The main features of the Caddx Gazer full-color night vision analog camera are as follows:

- **Ultra-Low Light Full-Color Night Vision:**
Still provides color images in extremely dark environments, breaking through the limitations of nighttime.
- **Detachable Filter:**
The filter can be freely removed or attached, preserving image quality during the day and enhancing brightness at night, suitable for all-weather use.
- **AI Image Enhancement:**
Clear details during the day, AI enhancement at night, maintaining clarity and high color reproduction.
- **Adjustable Zoom Function:**
Supports 3x magnification with stable image quality.

Installation Direction

*During installation, please ensure this side is facing upwards to prevent the image from being upside down.



Control Mode

Zoom Function:

Set one FC solder pad to output a PWM signal for control (use a knob switch for control). The FC outputs a PWM signal to perform zoom operations.
For example: when the PWM signal duty cycle is 100%, the image effect is 1x zoom; when the PWM signal duty cycle is 200%, the image effect is 2x zoom.

Reset Function:

Set one FC solder pad with a TX-defined IO to trigger the switch. This allows direct switching from high magnification to 1x, and restores the zoom focus when turned off.

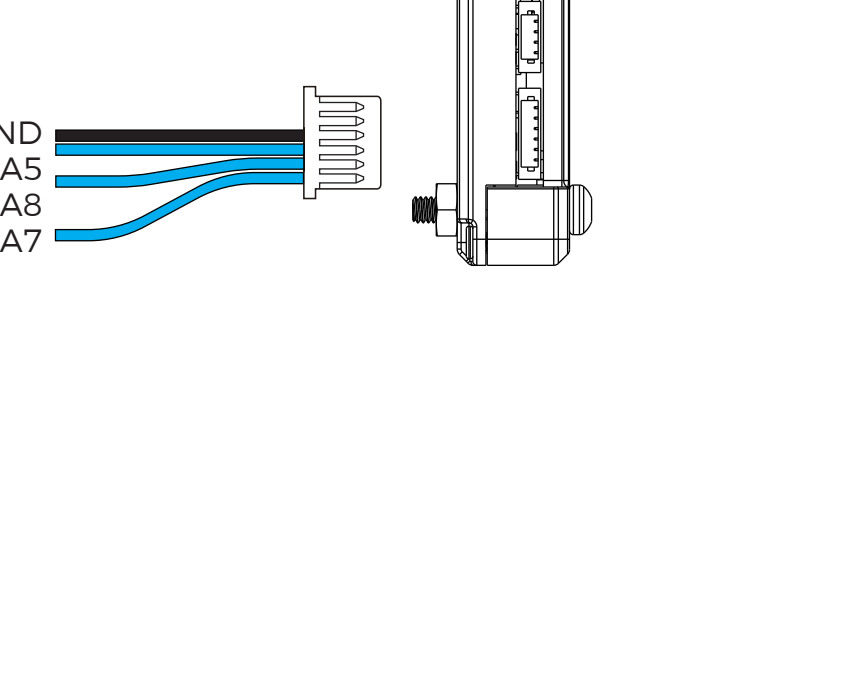
Reset Function (Day/Night Mode Switch):

Set one FC solder pad with a TX-defined IO to trigger the day/night mode switch each time.
(Day mode requires the use of a filter, while night mode does not require a filter.)

Connection

Power / CVBS Connection:

- 1.POWER: FC solder pad, 9-24V
- 2.GND: Connect to the GND
- 3.CVBS: Connect to the FC CAM interface



Control Line Connection:

1. GND: Connect to the GND
2. 2A5: Zoom reset switch
3. 2A8: Input PWM signal for zoom control
4. 2A7: Input IO signal for controlling the day/night mode switch



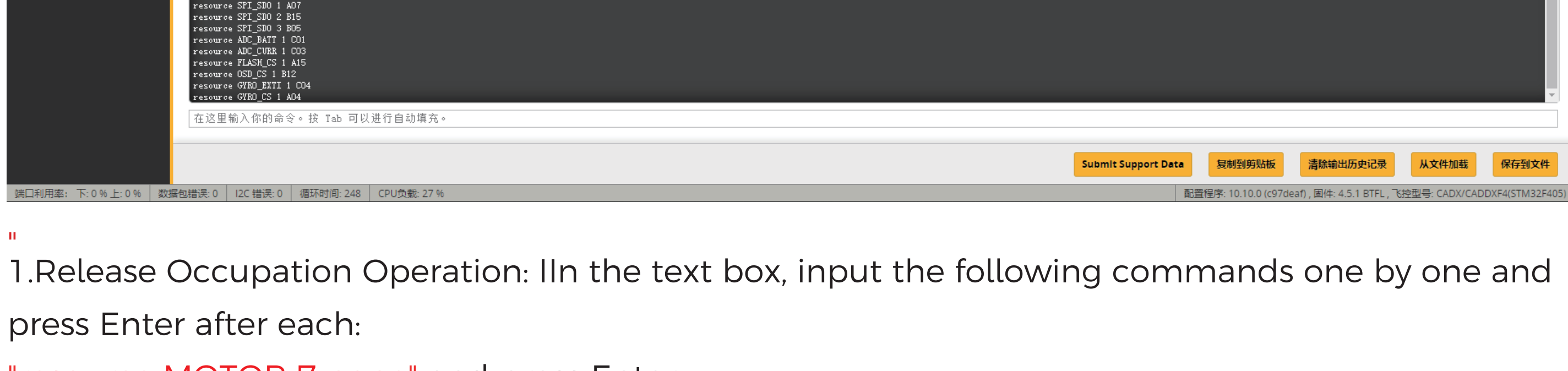
Debugging Procedure

*The following is an example; other solder pad definitions can be configured as needed.

The control lines are soldered as follows:

- 1.2A7: Connect to flight controller TX1
- 2.2A8: Connect to flight controller M7
- 3.2A5: Connect to flight controller TX6
- 4.GND: Connect to the GND

In the Betaflight program, select the "CLI" option from the menu bar. In the text box, enter the command "resource" to load and view the pin definitions, as shown in the image below:



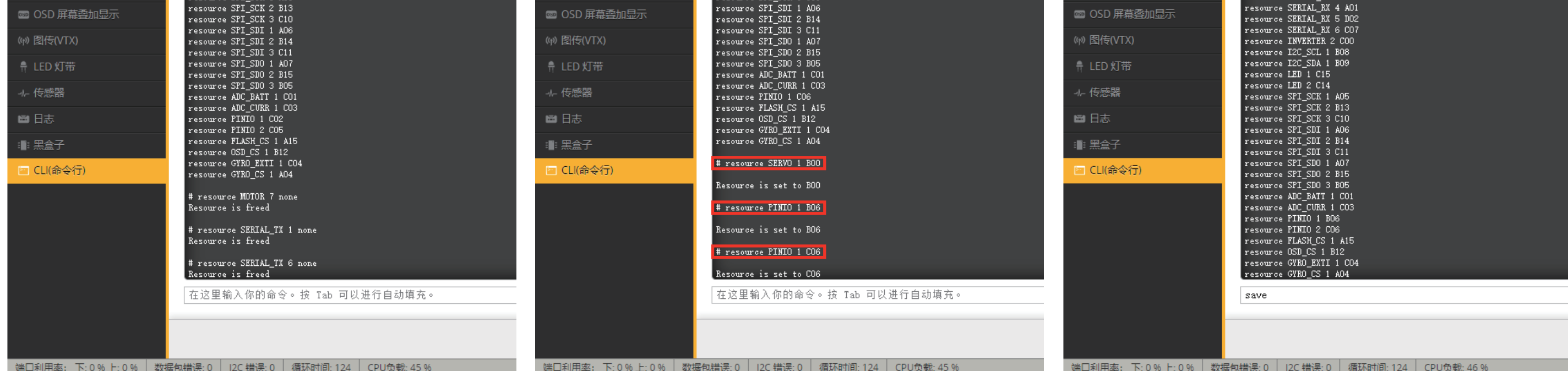
1.Release Occupation Operation: In the text box, input the following commands one by one and press Enter after each:

"resource MOTOR 7 none" and press Enter
"resource SERIAL_TX 1 none" and press Enter
"resource SERIAL_TX 6 none" and press Enter to unassign.

2.Configuration Definition Operation: In the text box, input the following commands one by one and press Enter after each:

"resource SERVO 1 B00" and press Enter
"resource PINIO 1 B06" and press Enter
"resource PINIO 2 C06" and press Enter to configure.

After completing the configuration, input "Save" in the text box and press Enter to save, as shown in the image below:



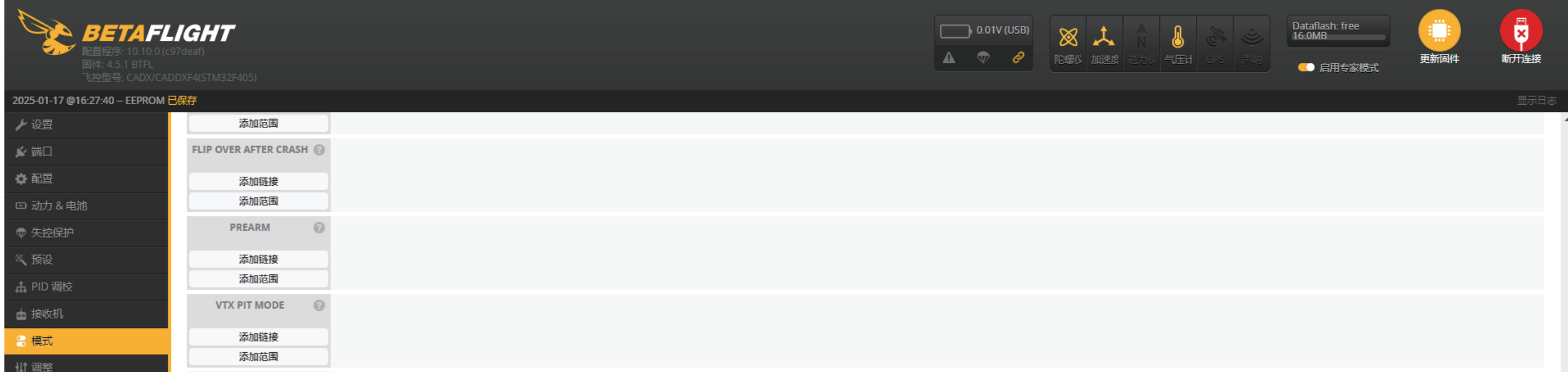
① Release Occupation Operation

② Configuration Definition Operation

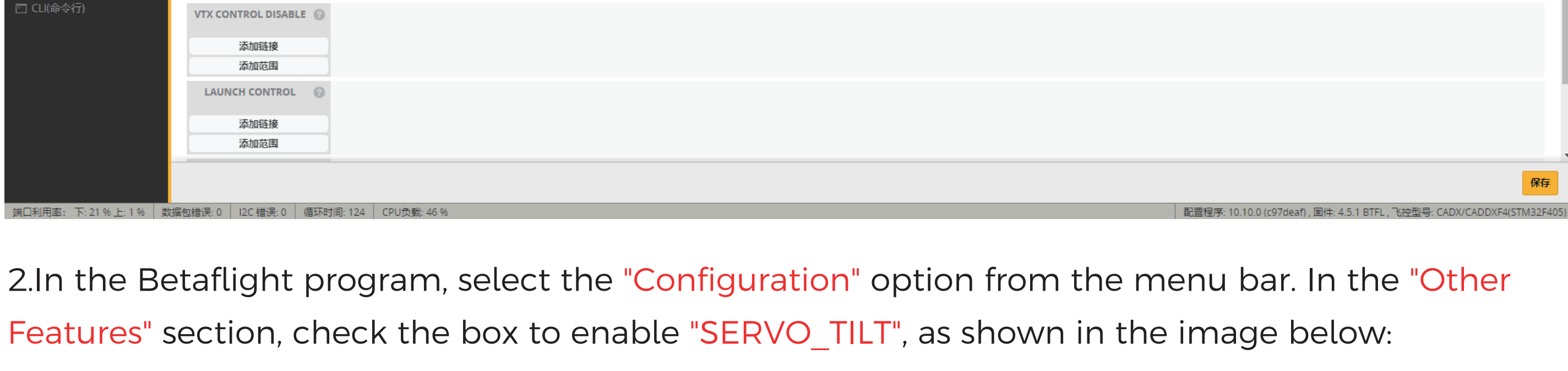
③ Save

RC Channel Configuration:

In the Betaflight program, select the "Modes" option from the menu bar. Find "USER1" and click to start debugging. If Channel 4 is set to a 2-position switch, select the "AUX 4" channel. Then find "USER2" and click to start debugging. If Channel 5 is set to a 2-position switch, select the "AUX 5" channel, as shown in the image below:



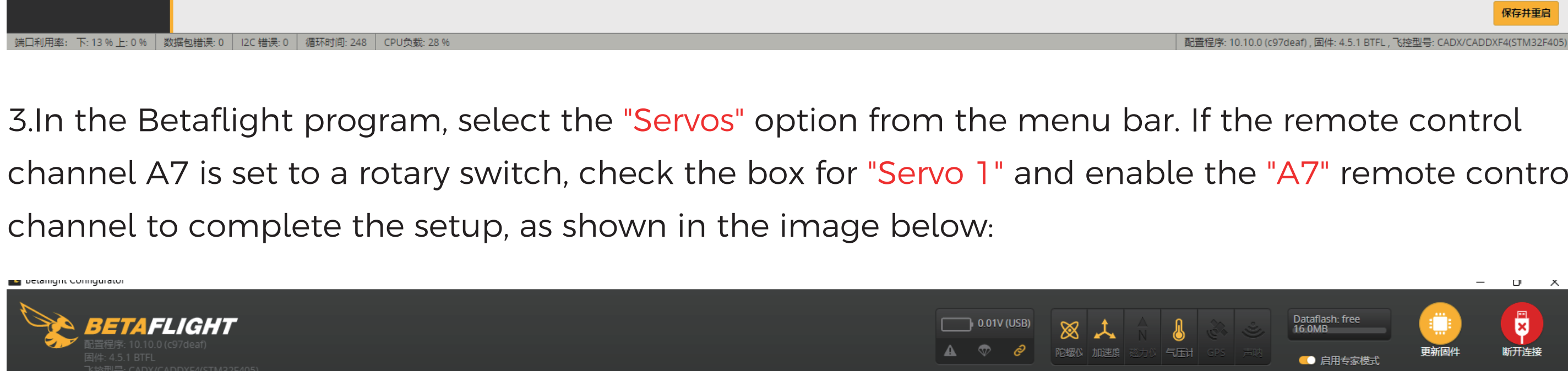
2.In the Betaflight program, select the "Configuration" option from the menu bar. In the "Other Features" section, check the box to enable "SERVO_TILT", as shown in the image below:



3.In the Betaflight program, select the "Servos" option from the menu bar. If the remote control channel A7 is set to a rotary switch, check the box for "Servo 1" and enable the "A7" remote control channel to complete the setup, as shown in the image below:



3.In the Betaflight program, select the "Servos" option from the menu bar. If the remote control channel A7 is set to a rotary switch, check the box for "Servo 1" and enable the "A7" remote control channel to complete the setup, as shown in the image below:



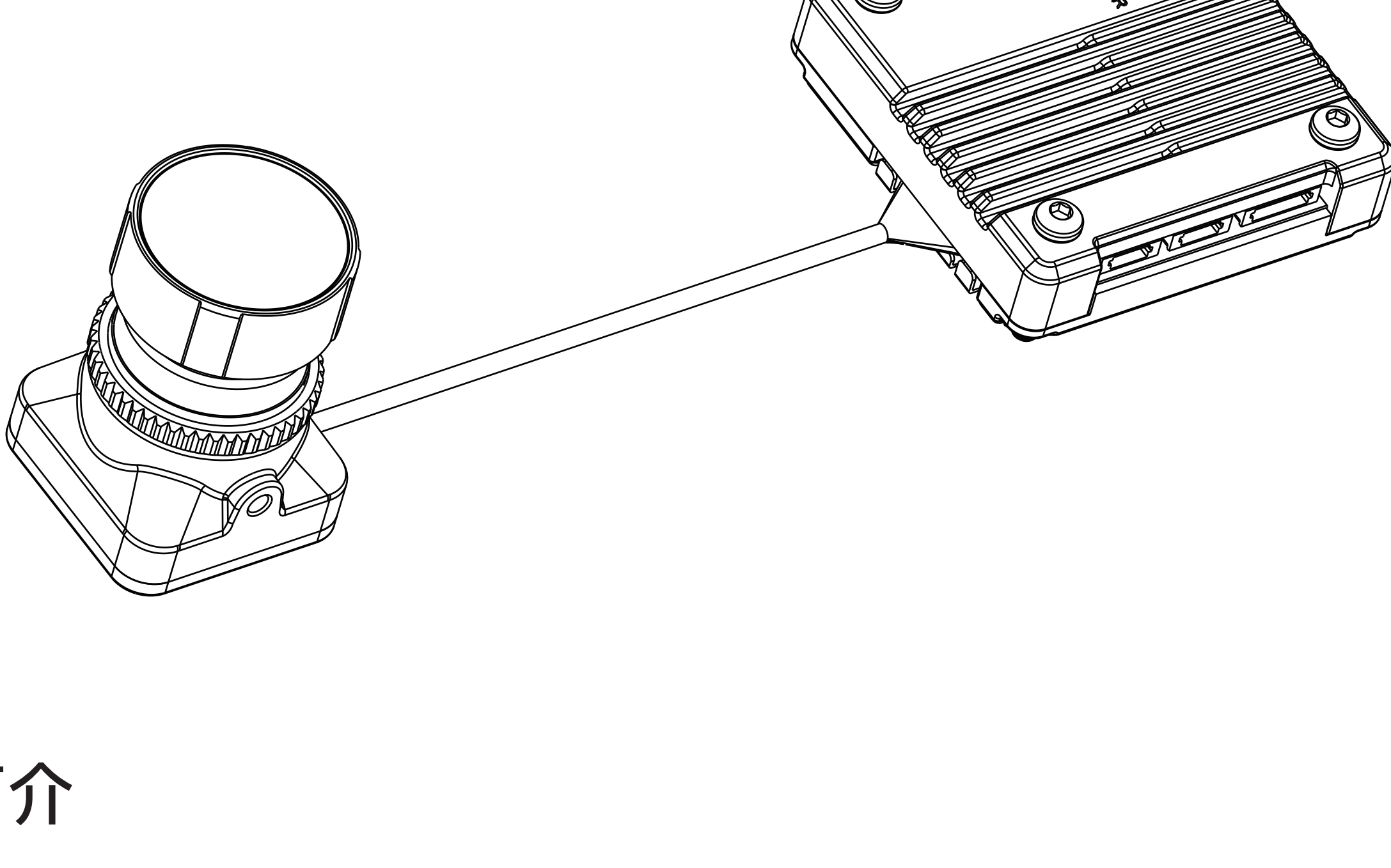
Specifications

Model	Caddx Gazer
Image sensor	1/1.8 inch
Resolution	1920x1080 (2MP)
Horizontal resolution	1500TVL
Focal length	2.8mm
Aperture	F1.0
FOV	131.6°
Filter	Manually removable
Output format	PAL
Frame rate	50fps
Magnification	3x (zoomed in by FC)
Image quality	D/N (switched by FC) It is recommended to install the filter and use N mode during the day, and remove the filter and use N mode at night
Aspect ratio	4:3
Video interface	1xPAL
Supply Voltage	9-24V
Typical Power Consumption	<2W
Operating temperature	-20℃ -60℃
Dimensions	Camera: 20x20x28.54mm AI Box: 34x34x8.65mm

Caddx Gazer

使用说明

V1.0



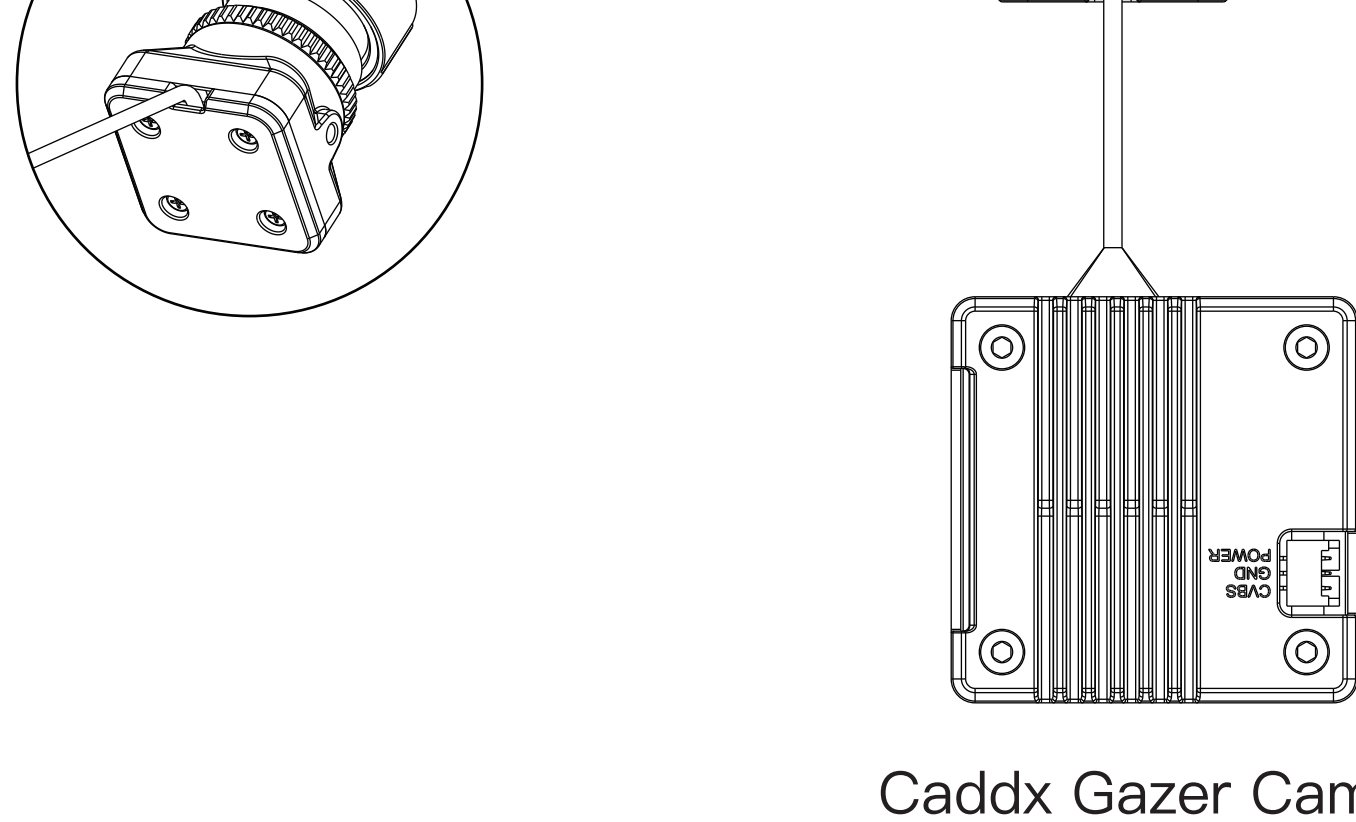
产品简介

Caddx Gazer 全彩夜视模拟相机主要特征如下:

- **超低照度夜视全彩:**
在极暗环境下仍能呈现彩色画面，突破夜间限制；
- **可拆卸滤镜:**
滤镜可自由装卸，白天保画质，夜晚增光，适应全天候使用；
- **AI 画质增强:**
白天细节清晰，夜间 AI 增强，画面依旧清晰，色彩高度还原；
- **可调变倍功能:**
支持3倍放大，画质稳定。

安装朝向

*安装时请根据此画面朝向向上，以免图像画面颠倒



Caddx Gazer Camera

产品功能

变倍功能: 设定1个飞控焊盘输出PWM信号进行控制 (控制拨杆使用旋钮开关) 飞控输出PWM信号实现变焦操作。

如：当PWM信号占空比为100时，图像效果为1倍放大；当PWM信号占空比为200时，图像效果为2倍放大。

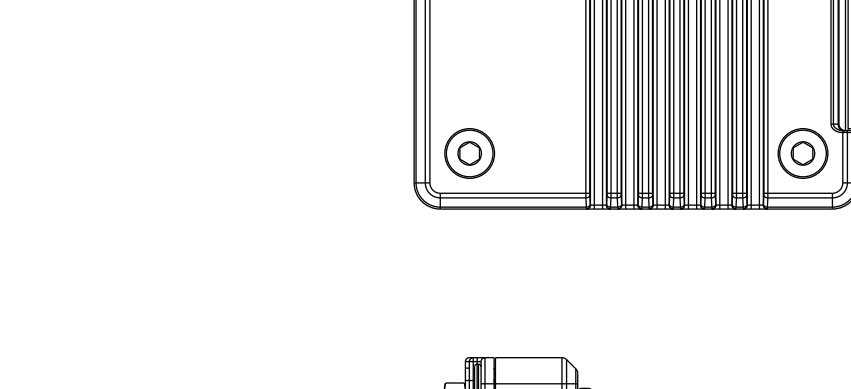
复位功能: 设定1个飞控焊盘TX定义IO进行控制触发开关可以从高倍率直接跳转至1倍，关闭后还原变倍焦距。

复位功能: 设定1个飞控焊盘TX定义IO进行控制每次触发进行白天模式/夜间模式切换。

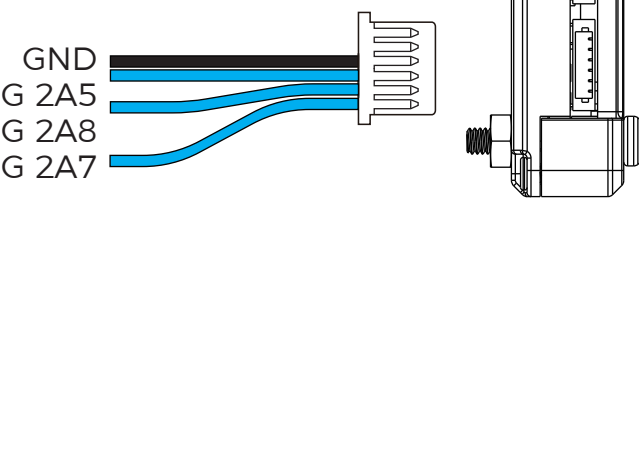
(白天模式需要配带滤镜黑夜则不配带滤镜)

接线方式

电源/CVBS接线: 1.POWER: 飞控焊盘9~24V
2.GND: 接负极线(GND)
3.CVBS接入飞控CAM接口



控制线接线: 1.GND: 接负极线(GND)
2.2A5: 倍率复位开关
3.2A8: 输入PWM信号用于变倍
4.2A7: 输入IO信号用于控制
白天模式/夜间模式切换

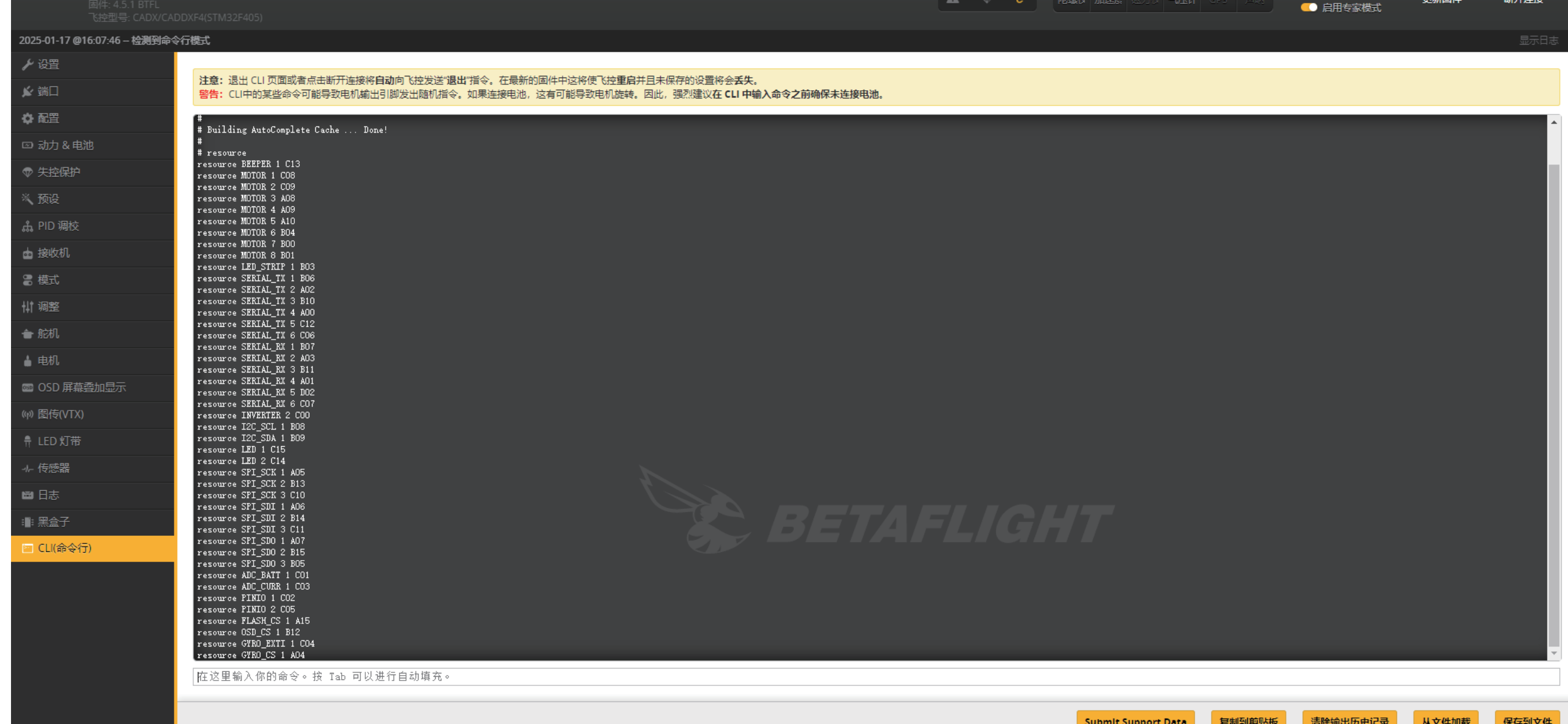


调式步骤

*以下为例，可自行配置其他焊盘定义

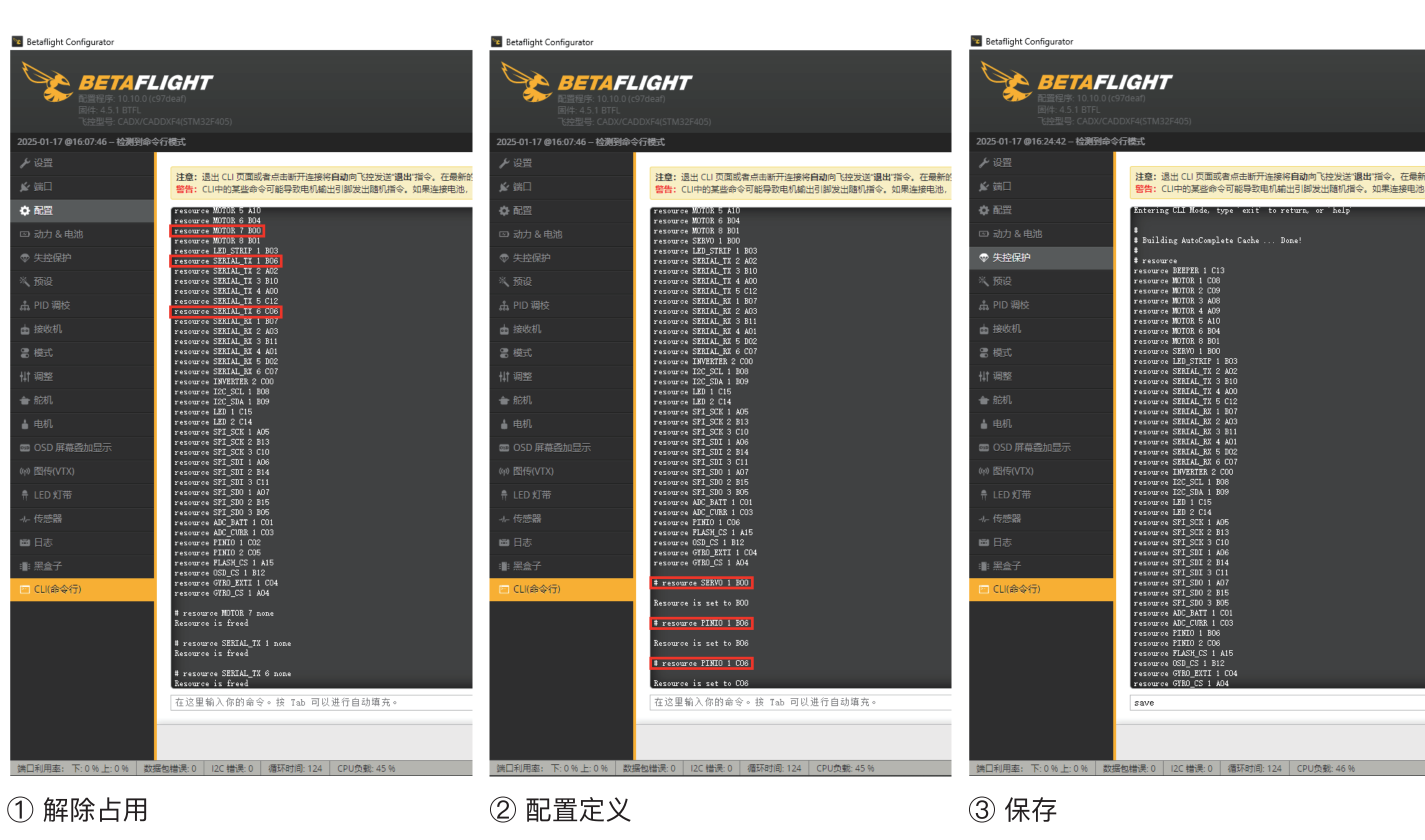
控制线硬件上焊接为：1.2A7：接入飞控TX1
2.2A8：接入飞控M7
3.2A5：接入飞控TX6
4.GND：接入负极线(GND)

在Betaflight程序中菜单栏选择“CLI”选项，在文本框输入命令“resource”加载查看引脚定义，如下图所示：



1.解除占用操作：文本框依次输入“resource MOTOR 7 none”回车；“resource SERIAL_TX 1 none”回车；“resource SERIAL_TX 6 none”回车进行解除；

2.配置定义操作：文本框依次输入“resource SERVO 1 B00”回车；“resource PINIO 1 B06”回车；“resource PINIO 2 C06”回车进行配置，完成后在文本框输入“Save”回车即可保存，如下图所示：



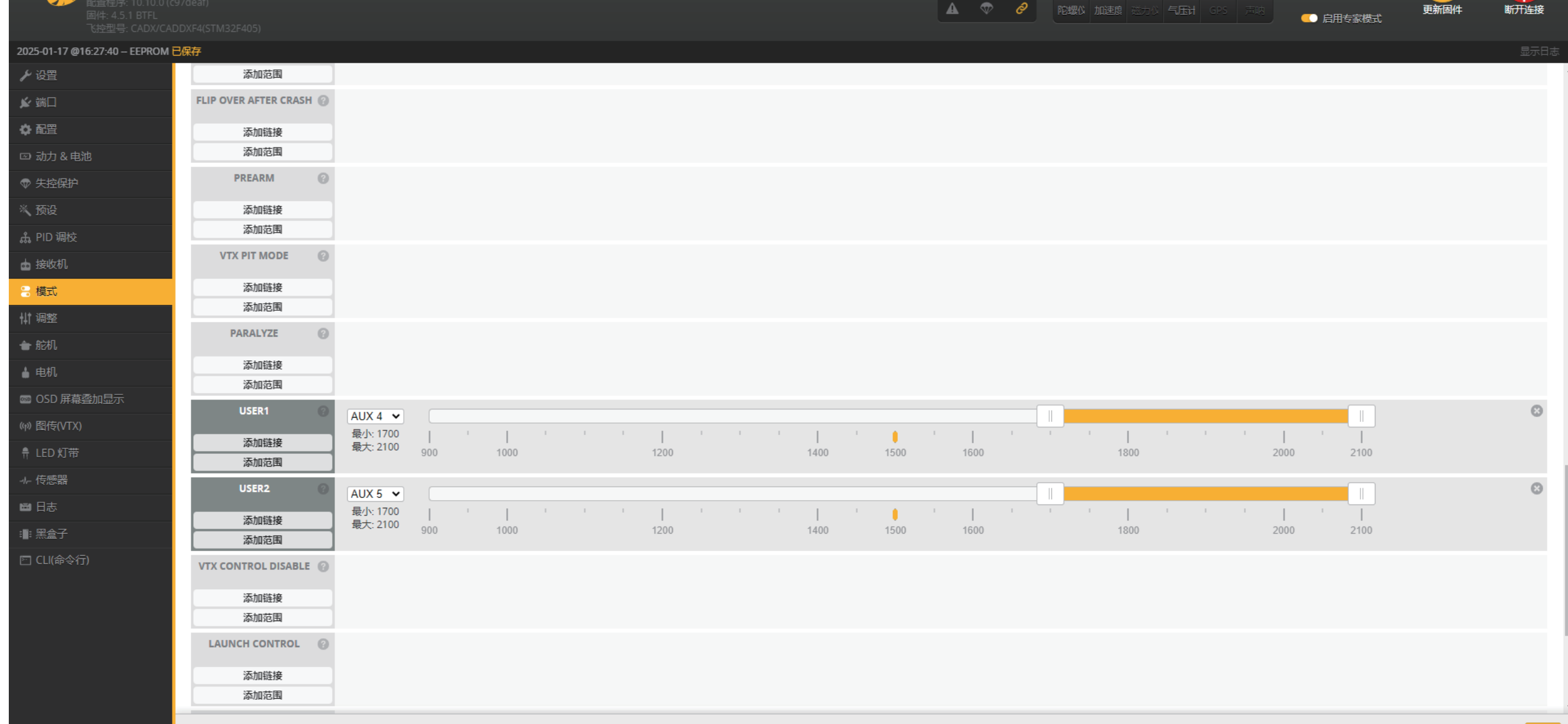
① 解除占用

② 配置定义

③ 保存

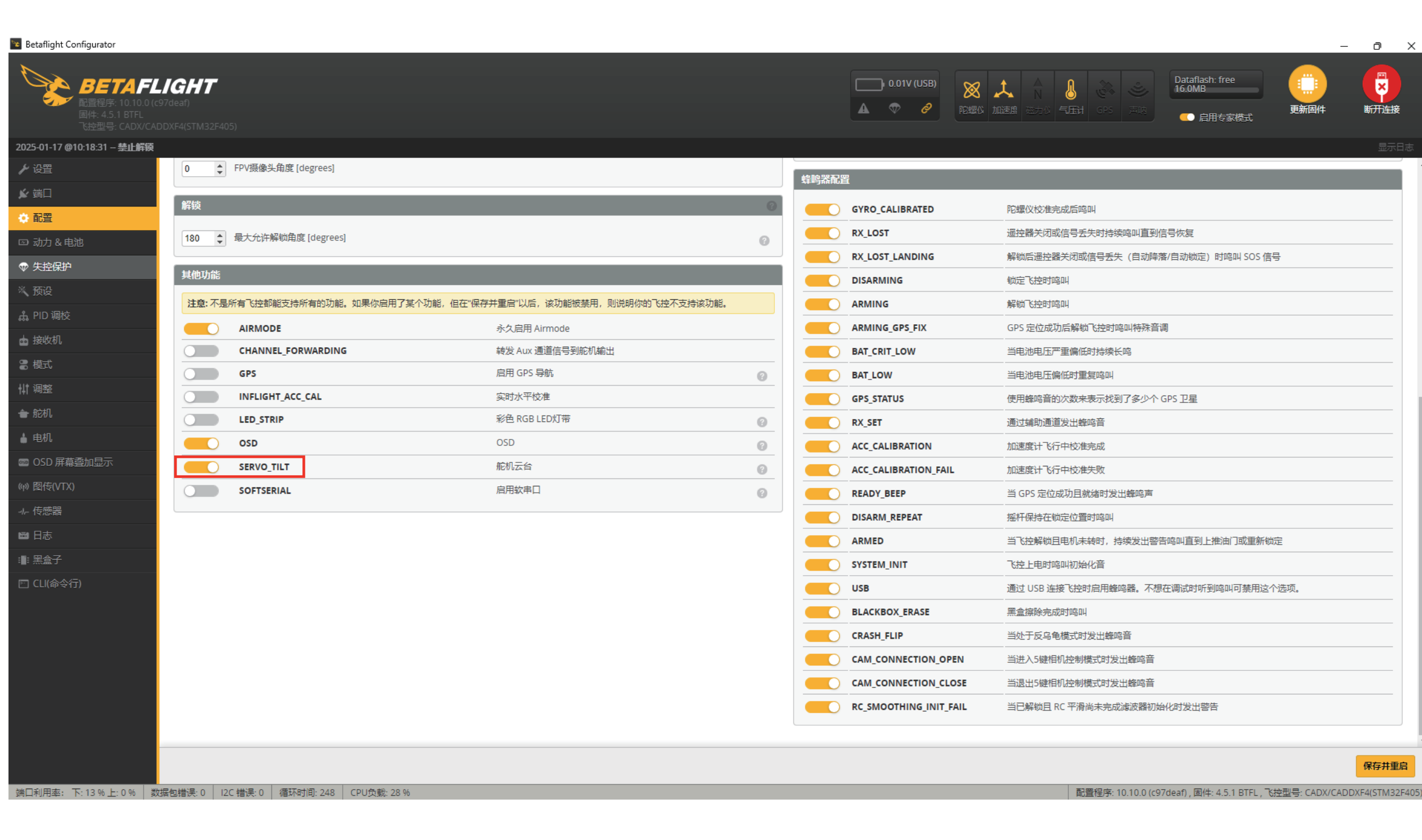
遥控器通道设置：

1.在Betaflight程序中菜单栏选择“模式”选项，找到“USER1”点击进行调试，当前通道4为二段拨杆时，则选择“AUX 4”通道，找到“USER2”点击进行调试，当前通道5为二段拨杆时，则选择“AUX 5”通道如下图片所示：

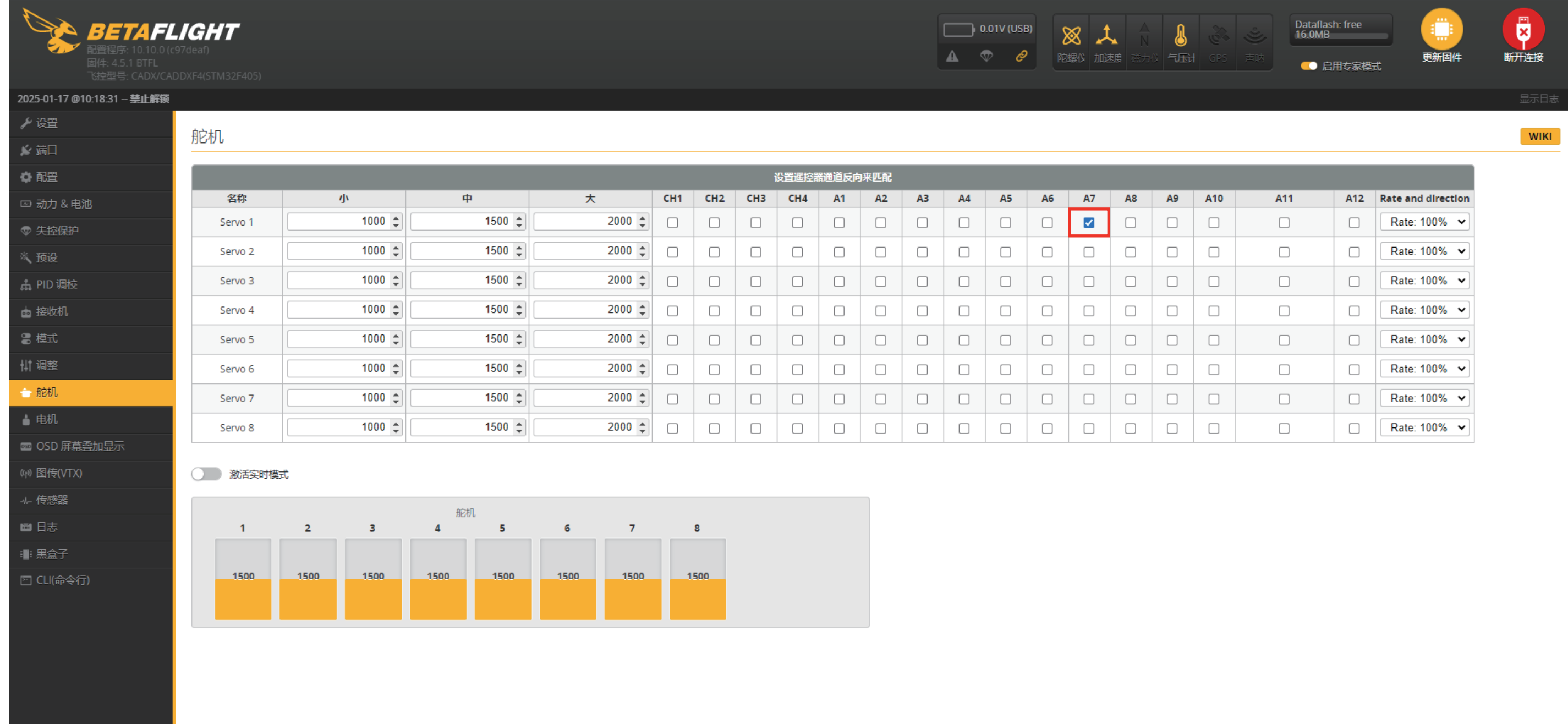


2.然后在Betaflight程序中菜单栏选择“配置”选项，在“其他功能”界面中将“SERVO_TILT”勾选打开，如下图

所示：



3.最后在Betaflight程序中菜单栏选择“舵机”选项，如当前遥控器A7为旋钮开关时，可在“Servo 1”勾选打开“A7”遥控器通道即完成，如下图所示：



产品规格

型号	Caddx Gazer
图像传感器	1/1.8 inch
分辨率	1920x1080 (2MP)
水平分辨率	1500TVL
焦距	2.8mm
光圈	F1.0
FOV	131.6°
滤镜	手动可拆卸
输出格式	PAL
帧频	50fps
放大倍率	3倍 (通过飞控放大)
画质效果	D/N (通过飞控切换) 其中白天建议安装滤镜使用D模式，夜间建议拆卸滤镜使用N模式
画面比例	4:3
视频接口	1xPAL
供电范围	9~24V
功耗	<2W
工作温度	-20°C~60°C
尺寸	Camera: 20x20x28.54mm AI Box: 34x34x8.65mm

CADDXFVP Support

Email: support@caddxfpv.com